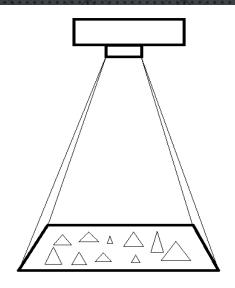
PRINCIPLES OF AERIAL PHOTOGRAPHY FOR FIRE MAPPING



OBJECTIVES

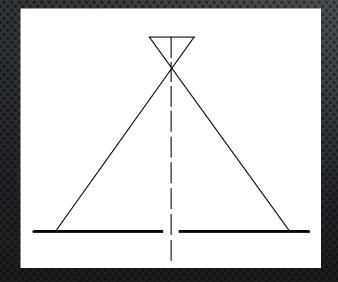
- Show the basic principles of collecting data for photogrammetry
- Show methods for collecting data on wildfire

Things to Consider for Product Quality

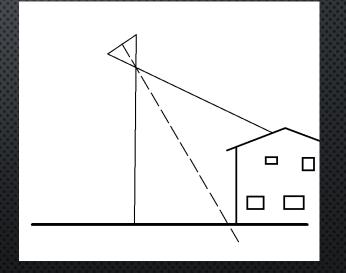
- Desired/Needed Resolution
- What is the desired product (3D model, Orthophoto, DEM, FMV)
- How precise does the product need to be
- Is the End Result feasible
- Are shadows a concern or needed
- Time required to acquire
- Is there a better way
- Weather/Wind

TWO BASIC CAMERA POSITIONS

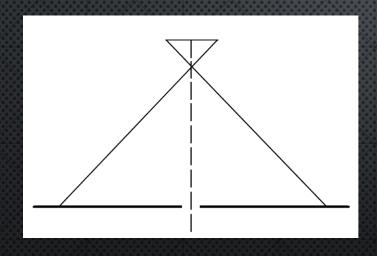
Vertical(Nadir)



Low oblique

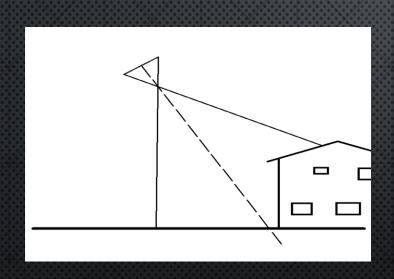


VERTICAL



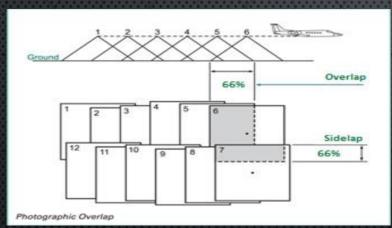
Most common position used for aerial mapping

LOW OBLIQUE



- Used to capture vertical faces in 3D modeling
- Multiple angles can be used
- Take care to not get the horizon in photos
- No more than 10 degrees offset from other data sets

OVERLAP/SIDELAP



Photogrammetry News

- For Photogrammetry software to align photos and have best results we use 66% sidelap and 66% overlap
- This needs to be based on the highest point in the area covered

GEOMETRY Base to Height Ratio

Base is the distance in sidelap from one photo to the next. Height is the altitude being flown Ideal Base to Height is <1:3

If flying at 100' with 66% sidelap flight lines are 44' apart.

100/44=2.27 The Base to Height is 1:2.27

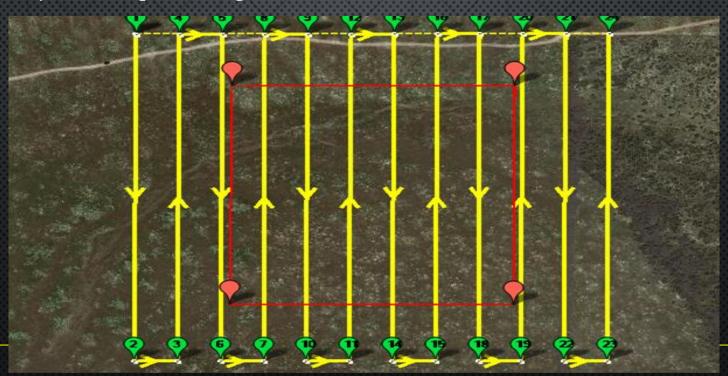
This means that the height accuracy of your model will be 2.27 times worse than the planimetric(horizontal plane) accuracy. It will manifest in the error values in Photoscan.

GEOMETRY Base to Height Ratio

With the current aircraft setups the camera top faces forward on the aircraft. The base distance is the same as the distance between flight lines. Height is altitude. Using the apps and programs as we teach and are setup this should not be a problem unless there is a wide variation in terrain (altitude changing with rolling terrain).

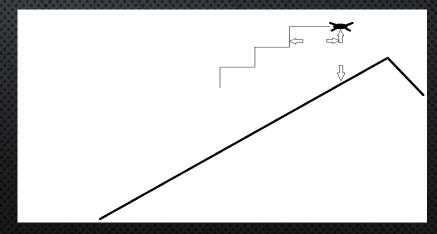
FLIGHT AREA VS. MAP AREA

A minimum of 3 flight lines are needed outside of the area of interest in order to have the geometry work in processing.



OVERLAP VS TERRAIN

- Altitude change can not be more than 50% of altitude of last transect or last picture
- This technique needs to be carefully planned out to not interfere with alignment and avoid CFIT



CAMERA CALIBRATION

- Needed for Software to determine distortions in camera lens
- For high quality data processing there needs to be photos with the camera turned +90 and -90 degrees from the primary direction.
- Simple orthophoto needs a few photos
- 3D models or volumetric require a high ratio of crossing flight lines

CAMERA TRIGGER TYPES

Intervalometer

- Camera triggering is done with timer in the camera
- + Consistent trigger timing
- Can't stop the triggering remotely
- Required to calculate trigger distance/speed

Autopilot Trigger

- Camera triggering is done by the autopilot
- + Only take photos of the required area
- - Periodic misfire of the trigger
- Use ODS to ensure proper operation

FLIGHT ALTITUDE

- Fly only as low as needed to meet objective
- Higher means fewer photos and lower resolution
- With the cameras we use figure 1cm per 100' for resolution.
- MicaSense cameras do about 2cm resolution per 100'

FLIGHT SPEED

- If flown too fast photos maybe blurry
- Consider time needed for camera to write to the SD card
- Depending on aircraft may not be adjustable

SPEED VS ALTITUDE

- The higher you are the faster you can fly
- Too fast and photos become blurry
- Use the Object Distance Spreadsheet to calculate

OBJECT DISTANCE SPREADSHEET

Input values in YELLOW boxes. Adjust speed, altitude, shutter speed to reach desired settings. Capture interval needs to be > than 1 second minimum.

Camera Model:			FLIR Duo EO	<select drop-dow<="" sensor="" th="" with=""><th>/n</th><th></th><th>NATIONAL S</th></select>	/n		NATIONAL S
Camera/Lens Parameters		Units:	Formula Notes:	Created by the BLM NOC Geospatial Section			
Width in Pixels	4000	pixels		Contact Mark Gapinski with q	uestions (mgapinski	@blm.gov)
Height in Pixels	3000	pixels					/
Image Sensor Width	7.6	mm			= Values	hange with	selected sensor
Image Sensor Height	5.7	mm			= Parame	ters to ente	r
Pixel Size	0.001900	mm/pix	Image Sensor Width / Width in Pixels		= Values	of note	
Lens Focal Length	8	mm		2 1			
magery Collection Parameters				Area of Intrest (AOI)		Units:	Formula N
Flying Speed	35	mph		AOI Width	5000	feet	
Flying Speed	15.65	m/sec		AOI Width	1524.00	meters	
Flying Speed	30.41	knots		AOI Height	5000	feet	
Flight Height (AGL)	2530	feet		AOI Height	1524.00	meters	
Flight Height (AGL)	771.14	meters		AOI Area	573.9	US acres	
Imagery GSD	0.1831	m/pix	Pixel Size * Flight Height / Lens Focal Length	Number of Flight Lines in AOI	7		AOI Width / Flight
Imagery GSD	18.315	cm/pix	3 0 7	Number of Images per Flight Line	9		AOI Height / Distance
Capture Interval	11.94	sec	Distance Between Images / Flying speed	Estimated Number of Images	63		Flight Lines in AOI * Ima
Minimum Required Shutter Speed 1/	300	sec	1/3 Pixel of Movement During Exposure	Estimated Survey Time	0:12:32	hh:mm:ss	Number of Images *
mage Footprint Size Footprint Width Footprint Height Footprint Width	732.59 549.44 2403.50	meters meters feet	Width in Pixels * GSD (m) Height in Pixels * GSD (m)	Ideal Camera Settings for	Stereo Im	nage Collec	tion 1
Footprint Width	1802.63	feet				erture Prio	
1 ootprint neight	1002.03	icet		Focus Distance		inity	y
Overlap and Sidelap				Shutter Speed		or Faster	
Overlap	66	%	Recommended Value of 66% (RedEdge-M 75%)	F-Stop (Aperture)	F 5.0	- F 8.0	
Distance Between Images	186.81	meters	Footprint Height * (100-Overlap)/100	ISO	100	- 1000	
Distance Between Images	612.89	feet			1015(7)		#score
Sidelap	66	%	Recommended Value of 66% (RedEdge-M 75%)				Direction of C
Flight Line Spacing	249.08	meters	Footprint Width * (100-Overlap)/100				
Fligth Line Spacing	817.19	feet					



nt Line Spacing

Between Images

ages per Flight Line

Capture Interval

Direction of Camera in Flight

SOLAR NOON

- Solar noon is when the sun crosses the meridian and is at its highest elevation in the sky, at 12 o'clock apparent solar time. The local or clock time of solar noon depends on the longitude and date.
- NOAA Solar Calculator

CAMERA SETTINGS

There are several settings that need to be set for quality imagery to be collected. Each setting can have an effect on others if changed.

SETTINGS

- Mode (Manual, Shutter Priority or Aperture Priority)
- Shutter Speed
- ISO
- F-Stop
- Focus

MODE

Shutter Priority – User set Shutter Speed and camera sets the F-Stop

 Aperture Priority – User sets F-Stop and camera sets the Shutter Speed

Manual – User defines settings for both

SHUTTER SPEED

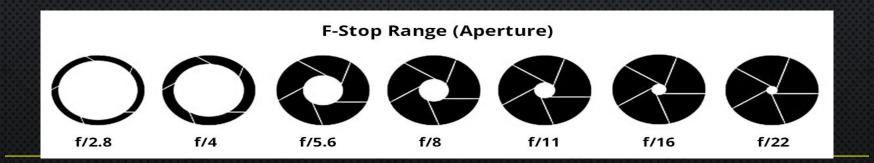
- Time the shutter is open at a given setting
- One of the controls to how much light is allowed in
- Expressed in fraction of 1 second
- 1/500th of a second will let in half as much light as 1/250th
- Too low speed will make photos blurry due to aircraft movement
- Typical for our use is 1/2000 to 1/3200

ISO

- ISO is a measurement of the sensitivity of the camera sensor
- Lower number is better, higher numbers the photos become grainy
- Typical settings for AP work is 100-400
- On a partly cloudy day consider floating the ISO

F-STOP

- Also called Aperture, is how far the shutter opens when a photo is taken.
- The smaller the F-Stop number the wider the shutter opens.



FOCUS

- Set to Infinity if possible for most projects
- For volumetric projects do not use auto focus as it will skew the model

INTER RELATIONSHIP

- It's all about how much light reaches the camera sensor
- A shutter speed of 1/50s with an *f*/4.0 aperture gives the same exposure value as a 1/100s shutter speed with an *f*/2.8 aperture, and also the same exposure value as a 1/200s shutter speed with an *f*/2.0 aperture, or 1/25th second at f/5.6.

EXPOSURE VALUE

- The F-Stop, Shutter Speed and scene luminance all determine the amount of light that reaches the camera sensor.
- EV Accounts for the Shutter Speed and F-Stop
- EV combined with ISO determines Under, Over or Properly Exposed photos

FOR AERIAL PHOTOGRAPHY WORK

- Typically will want a higher Shutter Speed to eliminate blur from aircraft movement 1/2000 to 1/3200 (Slower cloudy days, faster sunny days)
- An F-Stop of 8.0 to 5.6 (5.6 lower light, 8.0 brighter light)
- ISO 100-400 (lower bright light, higher low light)

TOM NOBLE ADVICE

- NO autofocus
- NO rolling shutter
- NO or very little image compression
- NO change in aperture
- NO motion blur

SHUTTER TYPE

Rolling Shutter

- Scans the scene and records to card one line at a time
- Scanning induces blur to the photos from moving aircraft

Global shutter

 Entire frame is captured at the same instant and recorded to the card

SHUTTER TYPE

Rolling Shutter



SHUTTER TYPE

Global Shutter



PHOTO FILE FORMATS

- JPEG
 - Most common used, compressed
- RAW
 - Used in event that adjustment is required, no compression(lossless)
- TIFF
 - Used with FLIR and RedEdge cameras, no compression(lossless)

CHANGING CAMERA SETTINGS Ricoh GR2

- GR Remote App to change settings
- Triggering through AP or timer
- Sync tablet clock with GR
- TURN OFF WIRELESS BEFORE FLIGHT

CHANGING CAMERA SETTINGS DJI XT2

- Flight App to change settings
- For photogrammetry camera needs to be set to timer
- Build flight plan for which sensor is desired(Thermal has narrower FOV)

CHANGING CAMERA SETTINGS FLIR Vue Pro R

- FLIR UAS App to change settings
- Build flight plan for which sensor is desired
- Camera is connected via Bluetooth
- Care must be taken while making adjustments to not change calibration
- If calibration is off camera must go to factory for calibration

CHANGING CAMERA SETTINGS

MicaSense RedEdge

- Settings are done via website address and wireless on tablet
- Camera time is taken from the connected GPS module
- Triggering through AP or timer
- Tablet must be very close to camera to connect, a few inches
- Wireless is very low power and can not be turned off

SUMMARY

Questions?